# **PM054TP Brush DC Motor Series**

## **General Features**

- · Size 54 mm
- · Ball Bearing and Copper Graphite Brushes
- Torques up to 252.00 Oz-in Peak, 50.00 Oz-in continuous
- · Speeds up to 4100 RPM
- · Voltage rating up to 24 Vdc
- · 2 Pole Brush Design
- · Class F rated construction

#### **Available Options**

- · Encoder IMS Q or EQM35 Series
- · Connectors and Matting cables
- · Custom Shaft ends
- · Custom Winding (Voltage or Current)
- · Gearbox IMS EL52 Series



#### **Technical and Performance Data**

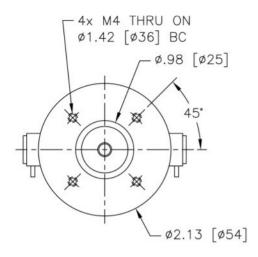
Model Number		PM054TP100	PM054TP300	PM054TP600	PM054TP700
General					
Terminal Voltage	Vdc	24.00	24.00	24.00	24.00
Continuous Stall Torque	Oz-in	18.31	26.63	38.62	50.46
	Nm	0.13	0.19	0.27	0.36
Continuous Current (3)	Amps	2.90	4.16	5.95	7.70
Peak Stall Torque	Oz-in	69.43	131.91	193.11	252.32
	Nm	0.49	0.93	1.36	1.78
Peak Current (3)	Amps	10.24	19.28	28.14	36.69
Rated Speed @ Terminal Voltage	RPM	3300	3600	3700	3600
Rated Torque @ Rated Speed	Oz-in	14.00	20.00	30.00	42.00
	Nm	0.10	0.14	0.21	0.30
Rated Output Power @ Rated Speed	Watts	34	53	82	112
Thermal Resistance	°C/W	9.0	8.0	7.0	5.0
Electrical					6 6 6 6 6
Torque Constant (± 10%), (2)	Oz-in/Amp	7.79	7.79	7.79	7.79
	Nm/Amp	0.0550	0.0550	0.0550	0.0550
Voltage Constant (± 10%), (2)	V/KRPM	5.77	5.77	5.77	5.77
	V s/rad	0.0550	0.0550	0.0550	0.0550
Resistance (± 15%), (2)	Ohms	1.73	0.92	0.50	0.41
Inductance ( ± 15%), (2)	mH	2.54	1.60	0.80	0.50
Mechanical					 
Inertia	Oz-In-Sec²	0.001629	0.003045	0.005240	0.006797
	kg m²	1.15E-05	2.15E-05	3.70E-05	4.80E-05
Maximum Speed (1)	RPM	4000	4100	4100	4000
Weight	Oz	21.2	31.7	45.9	56.4
	gm	600.00	900.00	1300.00	1600.00
Length	Inch	2.95	3.70	4.96	5.71
	mm	75.00	94.00	126.00	145.00

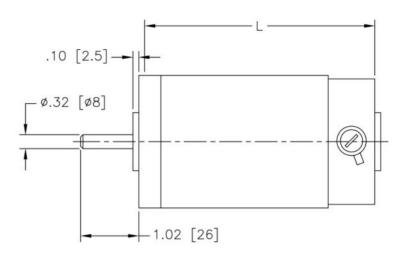
<sup>(1)</sup> Maximum Speed can by limited by bus voltage and feedback types

(2) Measure values at 20 °C

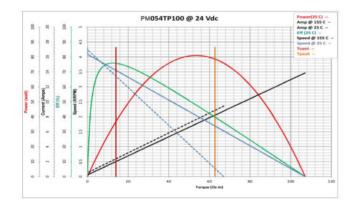
<sup>(3)</sup> Current values are at maximum allowable winding temperature 125 °C

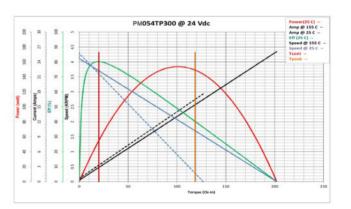
## **Outline Drawing and Dimensional Data**

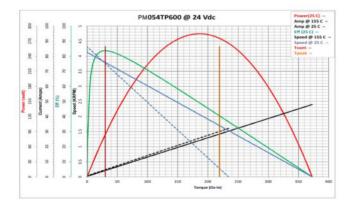


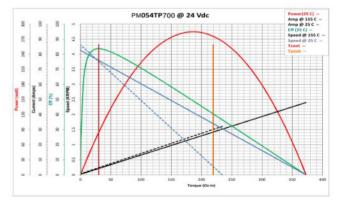


## **Performance Curves**









<sup>\*</sup> Motor performance curves may vary with the drive technology used

<sup>\*\*</sup> Motor performance curves may vary based upon the quality of the input voltage